

EPOS2 70/10

Positioning Controller

Hardware Reference



Document ID: rel2402

PLEASE READ THIS FIRST



These instructions are intended for qualified technical personnel. Prior commencing with any activities ...

- you must carefully read and understand this manual and
- you must follow the instructions given therein.

We have tried to provide you with all information necessary to install and commission the equipment in a **secure, safe and time-saving** manner. Our main focus is ...

- to familiarize you with all relevant technical aspects,
- to let you know the easiest way of doing,
- to alert you of any possibly dangerous situation you might encounter or that you might cause if you do not follow the description,
- to **write as little** and to **say as much** as possible and
- not to bore you with things you already know.

Likewise, we tried to skip repetitive information! Thus, you will find things **mentioned just once**. If, for example, an earlier mentioned action fits other occasions you then will be directed to that text passage with a respective reference.



Follow any stated reference – observe respective information – then go back and continue with the task!

PREREQUISITES FOR PERMISSION TO COMMENCE INSTALLATION

The **EPOS2 70/10** is considered as partly completed machinery according to EU's directive 2006/42/EC, Article 2, Clause (g) and therefore **is intended to be incorporated into or assembled with other machinery or other partly completed machinery or equipment**.



You must not put the device into service, ...

- unless you have made completely sure that the other machinery – the surrounding system the device is intended to be incorporated to – fully complies with the requirements stated in the EU directive 2006/42/EC!
- unless the surrounding system fulfills all relevant health and safety aspects!
- unless all respective interfaces have been established and fulfill the stated requirements!

TABLE OF CONTENTS

1	About this Document	5
2	Introduction	9
	2.1 Documentation Structure	9
	2.2 Safety Precautions.	10
3	Technical Data	11
	3.1 Electrical Data	11
	3.2 Mechanical Data	14
	3.3 Environmental Conditions	14
	3.4 Order Details	14
4	Connections	15
	4.1 Power Supply Connector (J1)	16
	4.2 Logic Supply Connector (J1A).	17
	4.3 Motor Connector (J2).	18
	4.3.1 maxon EC motor (brushless)	18
	4.3.2 maxon DC motor with separated Motor/Encoder Cable.	18
	4.4 Hall Sensor Connector (J3)	19
	4.5 Encoder Connector (J4).	20
	4.6 Signal 1 Connector (J5).	22
	4.6.1 Digital Inputs 1, 2 and 3	23
	4.6.2 Digital Inputs 4, 5 and 6	24
	4.6.3 Supply Voltage for DigOUTs	26
	4.6.4 Digital Outputs 1, 2 and 3	26
	4.6.5 Digital Output 4	27
	4.6.6 Digital Input 11	28
	4.7 Signal 2 Connector (J5A).	29
	4.7.1 Reference Output Voltage	29
	4.7.2 Analog Inputs 1 and 2	30
	4.7.3 Digital Inputs 7 and 8 "High Speed Command"	31
	4.8 Signal 3 Connector (J5B).	33
	4.8.1 Digital Input 9 "High Speed Command"	34
	4.8.2 Auxiliary Output Voltage	35
	4.8.3 Digital Output 5 "High Speed Output"	36
	4.9 RS232 Connector (J6).	37
	4.10 CAN Connector (J7, J8).	38
	4.11 USB Connector (J9).	39
	4.12 CAN Configuration (JP1)	40
	4.12.1 CAN ID (Node Address).	40
	4.12.2 CAN Bus Termination	41
	4.13 Status LEDs.	42

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1 About this Document

1.1 Intended Purpose

The purpose of the present document is to familiarize you with the described equipment and the tasks on safe and adequate installation and/or commissioning.

Observing the described instructions in this document will help you ...

- to avoid dangerous situations,
- to keep installation and/or commissioning time at a minimum and
- to increase reliability and service life of the described equipment.

Use for other and/or additional purposes is not permitted. maxon motor, the manufacturer of the equipment described, does not assume any liability for loss or damage that may arise from any other and/or additional use than the intended purpose.

1.2 Target Audience

This document is meant for trained and skilled personnel working with the equipment described. It conveys information on how to understand and fulfill the respective work and duties.

This document is a reference book. It does require particular knowledge and expertise specific to the equipment described.

1.3 How to use

Take note of the following notations and codes which will be used throughout the document.

Notation	Explanation
(n)	referring to an item (such as order number, list item, etc.)
→	denotes "see", "see also", "take note of" or "go to"

Table 1-1 Notations used in this Document

1.4 Symbols and Signs

1.4.1 Safety Alerts



Take note of when and why the alerts will be used and what the consequences are if you should fail to observe them!

Safety alerts are composed of...

- a signal word,
- a description of type and/or source of the danger,
- the consequence if the alert is being ignored, and
- explanations on how to avoid the hazard.

Following types will be used:

1) **DANGER**

Indicates an **imminently hazardous situation**. If not avoided, the situation will result in death or serious injury.

2) **WARNING**

Indicates a **potentially hazardous situation**. If not avoided, the situation **can** result in death or serious injury.

3) **CAUTION**

Indicates a **probable hazardous situation** and is also used to alert against unsafe practices. If not avoided, the situation **may** result in minor or moderate injury.

Example:



DANGER

High Voltage and/or Electrical Shock

Touching live wires causes death or serious injuries!

- Make sure that neither end of cable is connected to life power!
- Make sure that power source cannot be engaged while work is in process!
- Obey lock-out/tag-out procedures!
- Make sure to securely lock any power engaging equipment against unintentional engagement and tag with your name!

1.4.2 Prohibited Actions and Mandatory Actions

The signs define prohibitive actions. So, you **must not!**

Examples:



Do not touch!



Do not operate!

The signs point out actions to avoid a hazard. So, you **must!**

Examples:



Unplug!



Tag before work!

1.4.3 Informatory Signs



Requirement / Note / Remark

Indicates an action you must perform prior continuing or refers to information on a particular item.



Best Practice

Gives advice on the easiest and best way to proceed.



Material Damage

Points out information particular to potential damage of equipment.



Reference

Refers to particular information provided by other parties.

1.5 Trademarks and Brand Names

For easier legibility, registered brand names are listed below and will not be further tagged with their respective trademark. It must be understood that the brands (the below list is not necessarily concluding) are protected by copyright and/or other intellectual property rights even if their legal trademarks are omitted in the later course of this document.

The brand name(s) is/are a registered trademark(s) of ...
Adobe® Reader®	© Adobe Systems Incorporated, USA-San Jose, CA
Micro-Fit™ Mini-Fit Jr.™	© Molex, USA-Lisle, IL
Pentium®	© Intel Corporation, USA-Santa Clara, CA
Windows®	© Microsoft Corporation, USA-Redmond, WA

Table 1-2 Brand Names and Trademark Owners

1.6 Copyright

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2 Introduction

The present document provides you with information on the EPOS2 70/10 Positioning Controller's hardware. It contains...

- performance data and specifications,
- information on connections and pin assignment and
- wiring examples.

maxon motor control's EPOS2 70/10 is a small-sized, full digital, smart motion controller. Due to its flexible and high efficient power stage, the EPOS2 70/10 drives brushed DC motors with digital encoder as well as brushless EC motors with digital Hall sensors and encoder.

The sinusoidal current commutation by space vector control offers the possibility to drive brushless EC motors with minimal torque ripple and low noise. The integrated position, velocity and current control functionality allows sophisticated positioning applications. The EPOS2 70/10 is especially designed being commanded and controlled as a slave node in a CANopen network. In addition, the unit can be operated via any USB or RS232 interface.

Find the latest edition of the present document, as well as additional documentation and software to the EPOS2 70/10 Positioning Controller also on the internet:

→ www.maxonmotor.com – category «Service & Downloads»

→ shop.maxonmotor.com

2.1 Documentation Structure

The present document is part of a documentation set. Please find below an overview on the documentation hierarchy and the interrelationship of its individual parts:

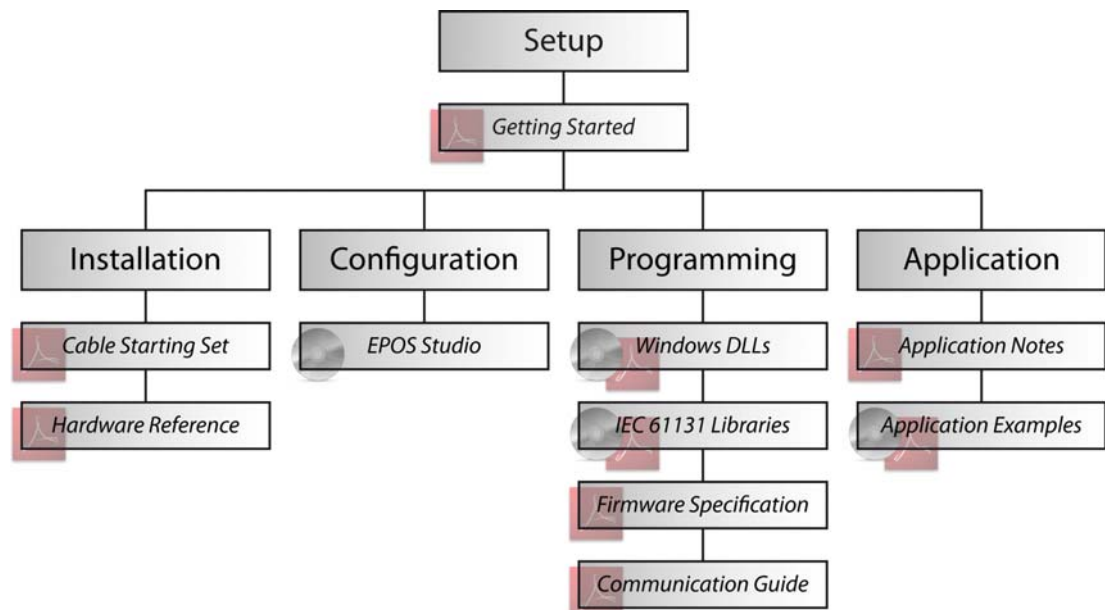


Figure 2-1 Documentation Structure

2.2 Safety Precautions

Prior continuing ...

- make sure you have read and understood chapter “ PLEASE READ THIS FIRST” on page A-2,
- do not engage with any work unless you possess the stated skills (→chapter “1.2 Target Audience” on page 1-5,
- refer to chapter “1.4 Symbols and Signs” on page 1-5 to understand the subsequently used indicators,
- you must observe any regulation applicable in the country and/or at the site of implementation with regard to health and safety/accident prevention and/or environmental protection,
- take note of the subsequently used indicators and follow them at all times.



DANGER

High Voltage and/or Electrical Shock

Touching live wires causes death or serious injuries!

- Consider any power cable as connected to life power, unless having proven the opposite!
- Make sure that neither end of cable is connected to life power!
- Make sure that power source cannot be engaged while work is in process!
- Obey lock-out/tag-out procedures!
- Make sure to securely lock any power engaging equipment against unintentional engagement and tag with your name!



Requirements

- Make sure that all associated devices and components are installed according to local regulations.
- Be aware that, by principle, an electronic apparatus can not be considered fail-safe. Therefore, you must make sure that any machine/apparatus has been fitted with independent monitoring and safety equipment. If the machine/apparatus should break down, if it is operated incorrectly, if the control unit breaks down or if the cables break or get disconnected, etc., the complete drive system must return – and be kept – in a safe operating mode.
- Be aware that you are not entitled to perform any repair on components supplied by maxon motor.



Best Practice

- For initial operation, make sure that the motor is free running. If not the case, mechanically disconnect the motor from the load.



Maximal permitted Supply Voltage

- Make sure that supply power is between 11...70 VDC.
- Supply voltages above 75 VDC will destroy the unit.
- Wrong polarity will destroy the unit.



Electrostatic Sensitive Device (ESD)

- Make sure to wear working cloth in compliance with ESD.
- Handle device with extra care.

3 Technical Data

3.1 Electrical Data

Rating	
Nominal power supply voltage V_{CC}	11...70 VDC
Nominal logic supply voltage V_C (optional)	11...70 VDC
Absolute minimum supply voltage	10 VDC
Absolute max. supply voltage	75 VDC
Max. output voltage	$0.9 \cdot V_{CC}$
Max. output current I_{max} (<1sec)	25 A
Continuous output current I_{cont}	10 A
Switching frequency	50 kHz
Max. efficiency	94%
Sample rate PI – current controller	10 kHz
Sample rate PI – speed controller	1 kHz
Sample rate PID – positioning controller	1 kHz
Max. speed @ sinusoidal commutation (motors with 1 pole pair)	25 000 rpm
Max. speed @ block commutation (motors with 1 pole pair)	100 000 rpm
Built-in motor choke per phase	25 μ H / 10 A

Table 3-3 Electrical Data – Rating

Inputs	
Hall sensor signals	Hall sensor 1, Hall sensor 2 and Hall sensor 3 for Hall effect sensor ICs (Schmitt trigger with open collector output)
Encoder signals	A, A\, B, B\, I, I\ (max. 5 MHz) internal line receiver EIA RS422 Standard
Digital Input 1 (“General Purpose”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 2 (“General Purpose”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 3 (“General Purpose”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 4 (“Home Switch”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 5 (“Positive Limit Switch”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 6 (“Negative Limit Switch”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Digital Input 7 (“High Speed Command”)	internal line receiver EIA RS422 Standard or (“Sin/Cos input”), resolution 12-bit, $\pm 1.8 \text{ V}$ (differential)
Digital Input 8 (“High Speed Command”)	internal line receiver EIA RS422 Standard or (“Sin/Cos input”), resolution 12-bit, $\pm 1.8 \text{ V}$ (differential)
Digital Input 9 (“High Speed Command”)	internal line receiver EIA RS422 Standard
Digital Input 11 (“Power Stage Enable”), optically isolated	+9...+24 VDC ($R_i = 1.8 \text{ k}\Omega$)
Analog Input 1	resolution 12-bit 0...+5 V (differential)
Analog Input 2	resolution 12-bit 0...+5 V (differential)
+V Opto IN	+12...+24 VDC
CAN ID (CAN identification)	ID 1...127 configurable via DIP switch or software

Table 3-4 Electrical Data – Inputs

Outputs	
Digital Output 1 (“General Purpose”), optically isolated	max. 24 VDC ($I_L < 20$ mA)
Digital Output 2 (“General Purpose”), optically isolated	max. 24 VDC ($I_L < 20$ mA)
Digital Output 3 (“General Purpose”), optically isolated	max. 24 VDC ($I_L < 20$ mA)
Digital Output 4 (“Brake”), optically isolated	max. 24 VDC ($I_L < 500$ mA)
Digital Output 5 (“High Speed Output”)	internal line driver EIA RS422 Standard

Table 3-5 Electrical Data – Outputs

Voltage Outputs	
Encoder supply voltage	+5 VDC ($I_L < 100$ mA)
Hall sensors supply voltage	+5 VDC ($I_L < 30$ mA)
Auxiliary output voltage	+5 VDC ($I_L < 150$ mA)
Reference output voltage	+5 VDC ($R_i = 1$ k Ω)

Table 3-6 Electrical Data – Voltage Outputs

Motor Connections	
maxon EC motor	maxon DC motor
Motor winding 1	+ Motor
Motor winding 2	- Motor
Motor winding 3	

Table 3-7 Electrical Data – Motor Connections

Interfaces		
RS232	RxD; TxD	max. 115 200 bit/s
USB 2.0 (full speed)	Data+; Data-	max. 12 Mbit/s
CAN 1	CAN_H (high); CAN_L (low)	max. 1 Mbit/s
CAN 2	CAN_H (high); CAN_L (low)	max. 1 Mbit/s

Table 3-8 Electrical Data – Interfaces

Status Indicators	
Operation	green LED
Error	red LED

Table 3-9 Electrical Data – LEDs

Connections		
Power Supply	On board: Suitable plug: Suitable terminal:	dual row male header (2 poles) Molex Mini-Fit Jr. dual row female receptacle (2 poles) Molex Mini-Fit Jr. 39-01-2020 female crimp terminal Molex Mini-Fit Jr. 44476-xxxx (AWG 16-20)
Logic Supply	On board: Suitable plug: Suitable terminal:	dual row male header (2 poles) Molex Mini-Fit Jr. dual row female receptacle (2 poles) Molex Mini-Fit Jr. 39-01-2020 female crimp terminal Molex Mini-Fit Jr. 44476-xxxx (AWG 16-20)
Motor	On board: Suitable plug: Suitable terminal:	dual row male header (4 poles) Molex Mini-Fit Jr. dual row female receptacle (4 poles) Molex Mini-Fit Jr. 39-01-2040 female crimp terminal Molex Mini-Fit Jr. 44476-xxxx (AWG 16-20)
Hall	On board: Suitable plug: Suitable terminal:	dual row male header (6 poles) Molex Micro-Fit 3.0 dual row female receptacle (6 poles) Molex Micro-Fit 3.0 430-25-0600 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
Encoder	On board: Suitable locking clip:	Plug DIN41651 (10 poles) for flat band cable, pitch 1.27mm, AWG 28 Tyco C42334-A421-C42 (right) / Tyco C42334-A421-C52 (left)
Signal 1	On board: Suitable plug: Suitable terminal:	dual row male header (6 poles) Molex Micro-Fit 3.0 dual row female receptacle (6 poles) Molex Micro-Fit 3.0 430-25-0600 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
Signal 2	On board: Suitable plug: Suitable terminal:	dual row male header (16 poles) Molex Micro-Fit 3.0 dual row female receptacle (16 poles) Molex Micro-Fit 3.0 430-25-1600 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
Signal 3	On board: Suitable plug: Suitable terminal:	dual row male header (12 poles) Molex Micro-Fit 3.0 dual row female receptacle (12 poles) Molex Micro-Fit 3.0 430-25-1200 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
RS232	On board: Suitable plug: Suitable terminal:	dual row male header (6 poles) Molex Micro-Fit 3.0 dual row female receptacle (6 poles) Molex Micro-Fit 3.0 430-25-0600 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
USB	On board: Suitable plug:	USB connector type mini-B jack (5 poles) Standard USB cable with type mini-B plug connector (5 poles)
CAN 1	On board: Suitable plug: Suitable terminal:	dual row male header (4 poles) Molex Micro-Fit 3.0 dual row female receptacle (4 poles) Molex Micro-Fit 3.0 430-25-0400 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)
CAN 2	On board: Suitable plug: Suitable terminal:	dual row male header (4 poles) Molex Micro-Fit 3.0 dual row female receptacle (4 poles) Molex Micro-Fit 3.0 430-25-0400 female crimp terminal Molex Micro-Fit 3.0 43030-xxxx (AWG 20-30)

Table 3-10 Electrical Data – Connections

3.2 Mechanical Data

Mechanical Data	
Weight	approx. 330 g
Dimensions (L x W x H)	150 x 93 x 27 mm
Mounting plate	for M3 screws

Table 3-11 Mechanical Data

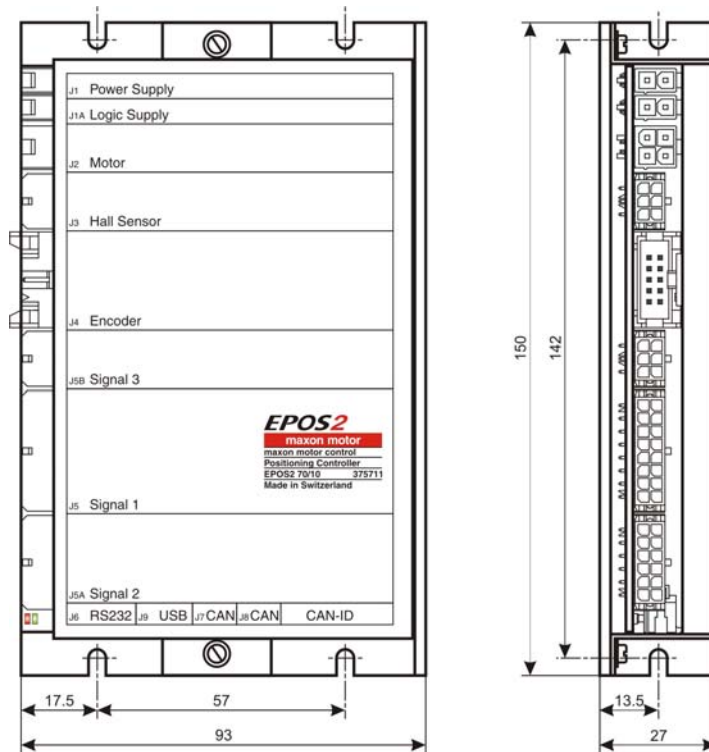


Figure 3-2 Dimensional Drawing [mm]

3.3 Environmental Conditions

Environmental Condition	
Temperature (operation / storage)	-10...+45°C / -40...+85°C
Humidity	20...80% (condensation not permitted)

Table 3-12 Environmental Conditions

3.4 Order Details

Order Details	
EPOS2 70/10	Order number 375711

Table 3-13 Order Details

4 Connections



Figure 4-3 Interfaces – Designations and Location

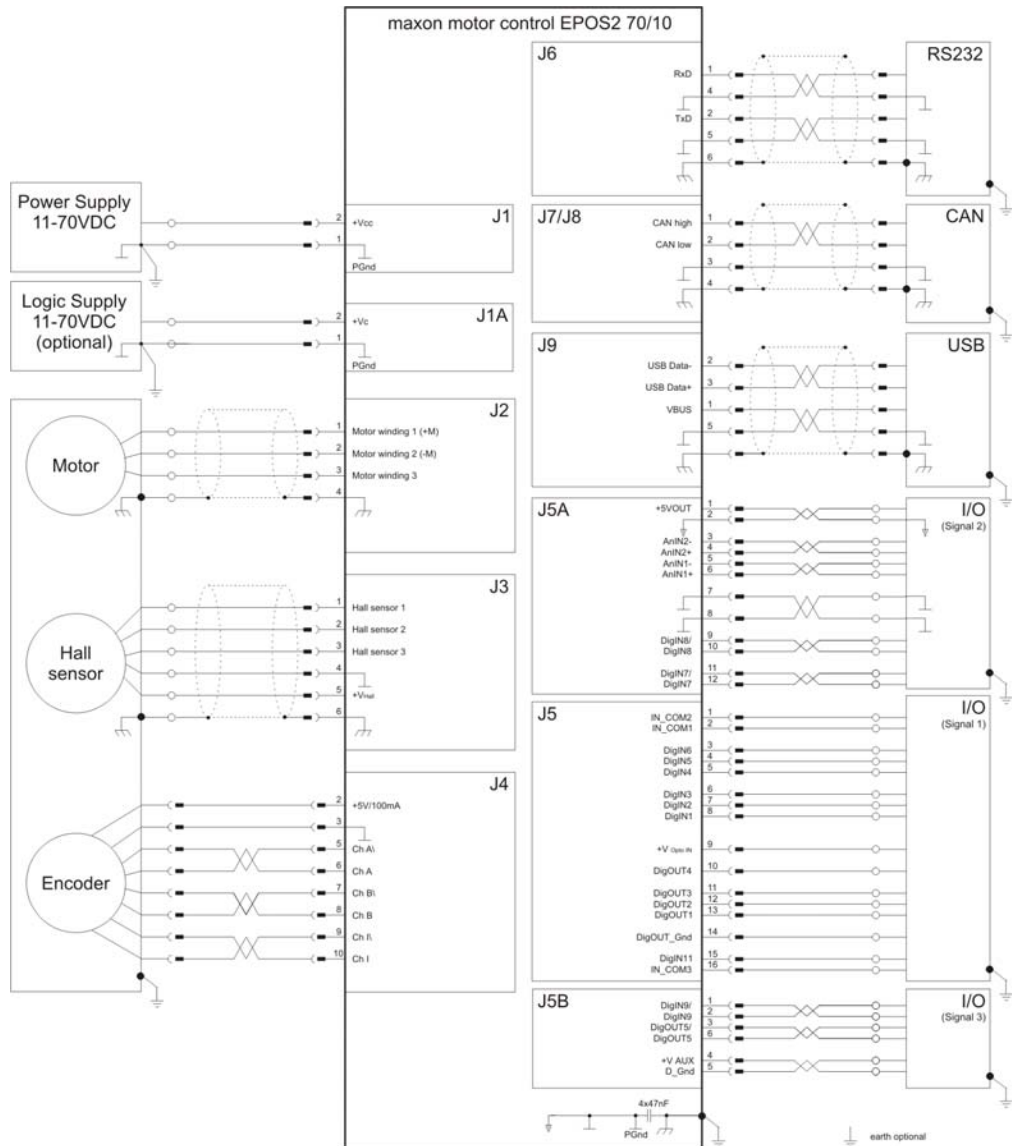


Figure 4-4 Wiring Diagram

4.1 Power Supply Connector (J1)



Best Practice

Keep the motor mechanically disconnected during setup and adjustment phase.

Determination of Power Supply

Basically, any power supply may be used, provided it meets below stated minimal requirements.

Power Supply Requirements	
Output voltage	V _{CC} min. 11 VDC; V _{CC} max. 70 VDC
Absolute output voltage	min. 10 VDC; max. 75 VDC
Output current	Depending on load (continuous max. 10 A / acceleration, short-time max. 25 A)

- 1) Calculate required voltage under load using following scheme (the formula takes a max. PWM cycle of 90% and a max. voltage drop of -1 V at EPOS2 70/10 into account):

Known values:

- Operating torque M_B [mNm]
- Operating speed n_B [min⁻¹]
- Nominal motor voltage U_N [Volt]
- Motor no-load speed at U_N, n₀ [min⁻¹]
- Speed/torque gradient of the motor Δn/ΔM [min⁻¹ mNm⁻¹]

Sought value:

- Supply voltage V_{CC} [Volt]

Solution:

$$V_{CC} = \frac{U_N}{n_0} \cdot \left(n_B + \frac{\Delta n}{\Delta M} \cdot M_B \right) \cdot \frac{1}{0.9} + 1 [V]$$

- 2) Choose power supply capable as to above calculation. Thereby consider:
 - a) During braking of the load, the power supply must be capable of buffering the fed back energy, e.g. in a capacitor.
 - b) When using an electronically stabilized power supply, observe that the overcurrent protection must not be activated in any operating state.

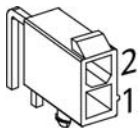


Figure 4-5 Power Connector (J1)

Pin	Signal	Description
1	Power_Gnd	Ground of supply voltage
2	+V _{CC}	Power supply voltage +11...+70 VDC

Accessories	Cable	EPOS Power Cable (275829)
Notes	Suitable connector	Molex Mini-Fit Jr. 2 poles (39-01-2020)
	Suitable crimp terminals	Molex Mini-Fit Jr. female crimp terminals (44476-xxxx)
	Suitable hand crimper	Molex hand crimper (63819-0900)

4.2 Logic Supply Connector (J1A)

By default, the logic is powered by the regular supply voltage. Optionally, you may wish to feed the logic supply voltage separately, permitting a safe and economical power backup feature.

Basically, any power supply may be used, provided it meets below stated minimal requirements.

Power Supply Requirements	
Output voltage	V_c min. 11 VDC; V_c max. 70 VDC
Absolute output voltage	min. 10 VDC; max. 75 VDC
Min. output power	P_c min. 5 W



Figure 4-6 Power Connector (J1A)

Pin	Signal	Description
1	Power_Gnd	Ground of supply voltage
2	+ V_c	Logic supply voltage +11...+70 VDC

Accessories	Cable	EPOS Power Cable (275829)
Notes	Suitable connector	Molex Mini-Fit Jr. 2 poles (39-01-2020)
	Suitable crimp terminals	Molex Mini-Fit Jr. female crimp terminals (44476-xxxx)
	Suitable hand crimper	Molex hand crimper (63819-0900)

4.3 Motor Connector (J2)

The controller is set to drive either maxon EC motor (brushless) or maxon DC motor (brushed) with separated motor/encoder cable.

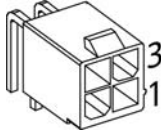


Figure 4-7 Motor Connector (J2)

Accessories	Cable	EPOS Motor Cable (275851)
Notes	Suitable connector Suitable crimp terminals Suitable hand crimper	Molex Mini-Fit Jr. 4 poles (39-01-2040) Molex Mini-Fit Jr. female crimp terminals (44476-xxxx) Molex hand crimper (63819-0900)

4.3.1 maxon EC motor (brushless)

Pin	Signal	Description
1	Motor winding 1	EC motor: Winding 1
2	Motor winding 2	EC motor: Winding 2
3	Motor winding 3	EC motor: Winding 3
4	Motor shield	Cable shield

4.3.2 maxon DC motor with separated Motor/Encoder Cable

Pin	Signal	Description
1	Motor (+M)	DC motor: Motor +
2	Motor (-M)	DC motor: Motor -
3	do not connect	–
4	Motor shield	Cable shield

4.4 Hall Sensor Connector (J3)

Hall sensors are required to detect the rotor position of maxon EC motors (brushless).

Suitable Hall effect sensors IC use «Schmitt trigger» with open collector output.

Hall sensor supply voltage	+5 VDC
Max. Hall sensor supply current	30 mA
Input voltage	0...+24 VDC
Logic 0	typically <0.8 VDC
Logic 1	typically >2.4 VDC
Internal pull-up resistor	2.7 kΩ (against +5 VDC)

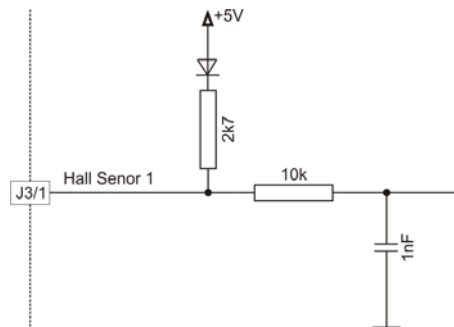


Figure 4-8 Hall Sensor Input Circuit

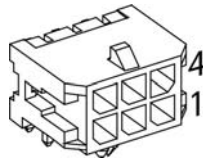


Figure 4-9 Hall Sensor Connector (J3)

Pin	Signal	Description
1	Hall sensor 1	Hall sensor 1 Input
2	Hall sensor 2	Hall sensor 2 Input
3	Hall sensor 3	Hall sensor 3 Input
4	GND	Ground of Hall sensor supply
5	+V _{Hall}	Hall sensor supply voltage +5 VDC / 30 mA
6	Hall shield	Cable shield

Accessories	Cable	EPOS Hall Sensor Cable (275878)
Notes	Suitable connector	Molex Micro-Fit 3.0 6 poles (430-25-0600)
	Suitable crimp terminals	Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx)
	Suitable hand crimper	Molex hand crimper (63819-0900)

4.5 Encoder Connector (J4)



Best Practice

The use of encoder with built-in line driver is mandatory.

Even though 2-channel will do, we strongly recommend to use only 3-channel versions!

Implemented are three high-speed RS422 receivers featuring fault detection circuitry and fault status outputs. The receivers' inputs feature fault thresholds that detect the device's "not in valid state".

The receivers indicate whether a receiver input is in open circuit condition (except index channel), short-circuit condition, or beyond the common mode range (smaller -10 V or higher +13.2 V). They also generate a fault indication if the differential input voltage drops below the 475 mV threshold.

By default, the controller is set for a 500 count per turn encoder. For other encoders, you will need to adjust respective settings via software.

Encoder supply voltage	+5 VDC
Max. encoder supply current	100 mA
Min. differential Input voltage	± 475 mV
Line receiver (internal)	EIA RS422 Standard
Max. encoder input frequency	5 MHz

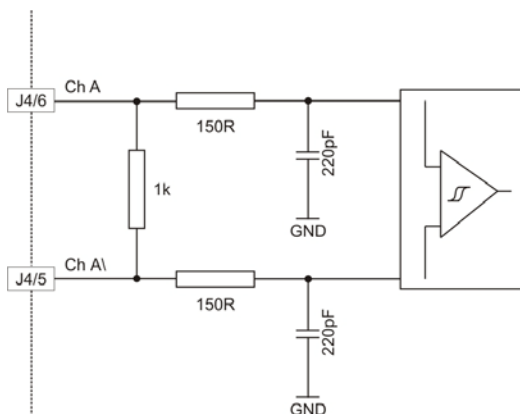


Figure 4-10 Encoder Input Circuit for Channel A (analogously valid also for Channel B)

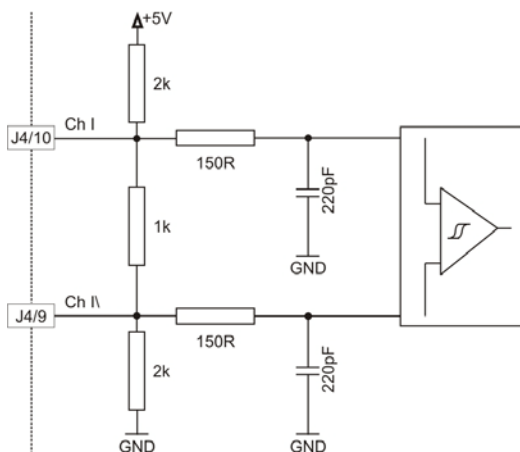


Figure 4-11 Encoder Input Circuit for Index Channel

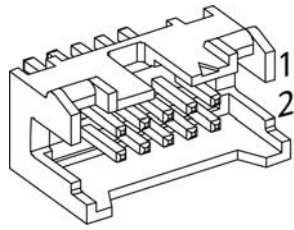


Figure 4-12 Encoder Connector (J4)

Pin	Signal	Description
1	not connected	–
2	+5 VDC / 100 mA	Encoder supply voltage
3	GND	Ground
4	not connected	–
5	Channel A\	Channel A complement
6	Channel A	Channel A
7	Channel B\	Channel B complement
8	Channel B	Channel B
9	Channel I\	Index complement
10	Channel I	Index



Best Practice

Among other encoders, pin out perfectly suits...

- maxon digital MR-Encoder type S, M, ML, L all with Line Driver
- maxon digital encoder HEDL 55_ with Line Driver RS422

Accessories	Cable	EPOS Encoder Cable (275934)
Notes	Suitable connector	DIN 41651 Plug, pitch 2.54 mm, 10 poles, plug strain relief

4.6 Signal 1 Connector (J5)

Contains smart multi-purpose digital I/Os configurable as...

- “Positive Limit Switch”
- “Negative Limit Switch”
- “Home Switch”
- “Brake Output”

Additionally available are “General Purpose” digital I/Os.

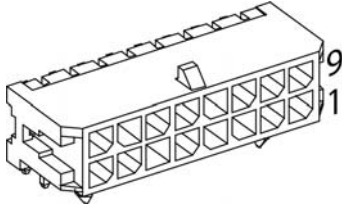


Figure 4-13 Signal 1 Connector (J5)

Pin	Signal	Description
1	IN_COM2	Common signal 2 for DigIN4...6
2	IN_COM1	Common signal 1 for DigIN1...3
3	DigIN6	Digital Input 6 “Negative Limit Switch”
4	DigIN5	Digital Input 5 “Positive Limit Switch”
5	DigIN4	Digital Input 4 “Home Switch”
6	DigIN3	Digital Input 3 “General Purpose”
7	DigIN2	Digital Input 2 “General Purpose”
8	DigIN1	Digital Input 1 “General Purpose”
9	+V Opto IN	External supply input voltage for DigOUTs (+12...24 VDC)
10	DigOUT4	Digital Output 4 “Brake”
11	DigOUT3	Digital Output 3 “General Purpose”
12	DigOUT2	Digital Output 2 “General Purpose”
13	DigOUT1	Digital Output 1 “General Purpose”
14	DigOUT_Gnd	DigOUT ground (referenced to +V Opto IN)
15	DigIN11	Digital Input 11 “Power Stage Enable”
16	IN_COM3	Common signal 3 for DigIN11

Accessories	Cable	EPOS Signal Cable 1 (275932)
Notes	Suitable connector	Molex Micro-Fit 3.0 16 poles (430-25-1600)
	Suitable crimp terminals	Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx)
	Suitable hand crimper	Molex hand crimper (63819-0000)

4.6.1 Digital Inputs 1, 2 and 3

By default, the optically isolated digital inputs are defined as “General Purpose” and may be configured via software.

DigIN1 “General Purpose” DigIN2 “General Purpose” DigIN3 “General Purpose” IN_COM1 (common signal)	Connector [J5] Pin [8] Connector [J5] Pin [7] Connector [J5] Pin [6] Connector [J5] Pin [2]
Type of input	Optically isolated, single-ended, bipolar
Input voltage	±24 VDC
Max. input voltage	±30 VDC
Logic 0	$ I_{in} < 1 \text{ mA} / U_{in} < 5 \text{ VDC}$
Logic 1	$ I_{in} > 3 \text{ mA} / U_{in} > 9 \text{ VDC}$
Input resistance	typically 1.8 kΩ @ 24 VDC
Input current at logic 1	typically 13.2 mA @ 24 VDC
Switching delay	<300 μs @ 24 VDC

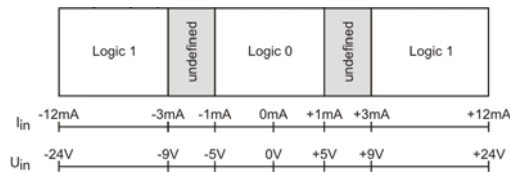


Figure 4-14 DigIN1...3 Logic Level

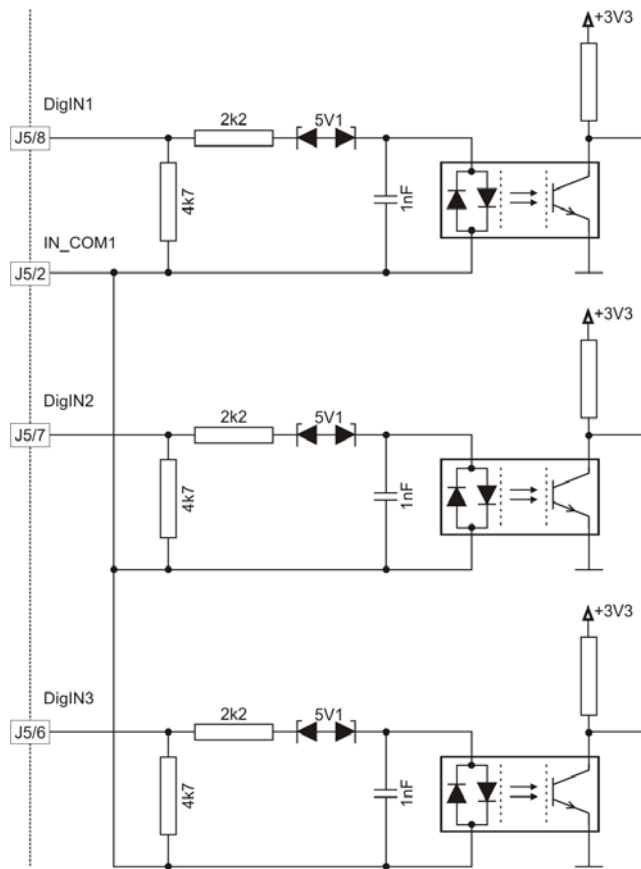


Figure 4-15 DigIN1...3 Circuit

4.6.2 Digital Inputs 4, 5 and 6

By default, the optically isolated digital inputs are defined as follows and may be configured via software.

- Digital Input 4 “Home Switch”
- Digital Input 5 “Positive Limit Switch”
- Digital Input 6 “Negative Limit Switch”

DigIN4 “Home Switch”	Connector [J5] Pin [5]
DigIN5 “Positive Limit Switch”	Connector [J5] Pin [4]
DigIN6 “Negative Limit Switch”	Connector [J5] Pin [3]
IN_COM2 (common signal)	Connector [J5] Pin [1]
Type of input	Optically isolated, single-ended, bipolar
Input voltage	±24 VDC
Max. input voltage	±30 VDC
Logic 0	$ I_{in} < 1 \text{ mA} / U_{in} < 5 \text{ VDC}$
Logic 1	$ I_{in} > 3 \text{ mA} / U_{in} > 9 \text{ VDC}$
Input resistance	typically 1.8 kΩ @ 24 VDC
Input current at logic 1	typically 13.2 mA @ 24 VDC
Switching delay	<300 μs @ 24 VDC

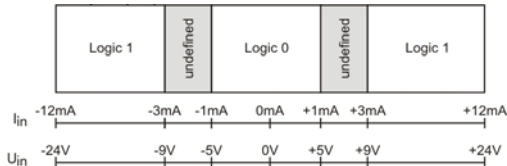


Figure 4-16 DigIN4...6 Logic Level

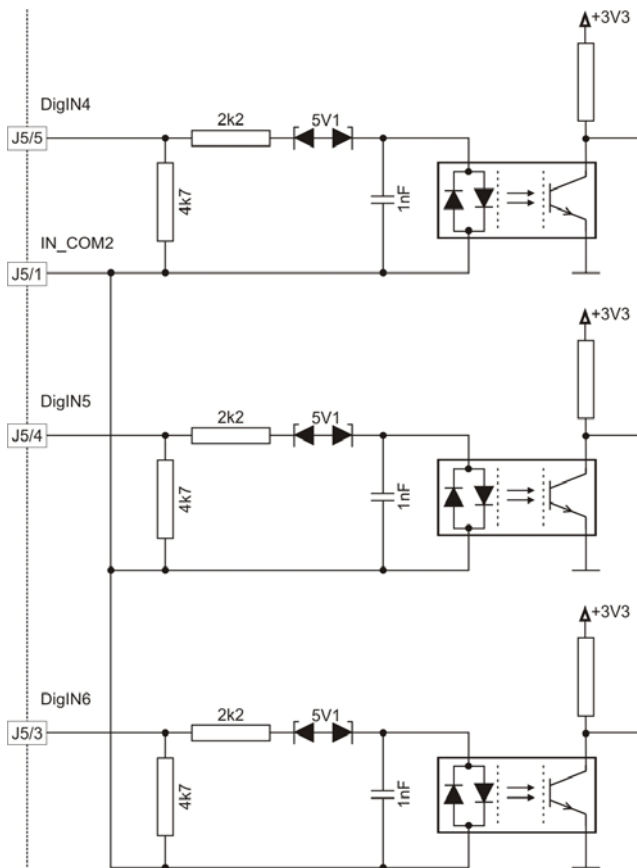


Figure 4-17 DigIN4...6 Circuit

Wiring Example: "Different Types of Proximity Switches"

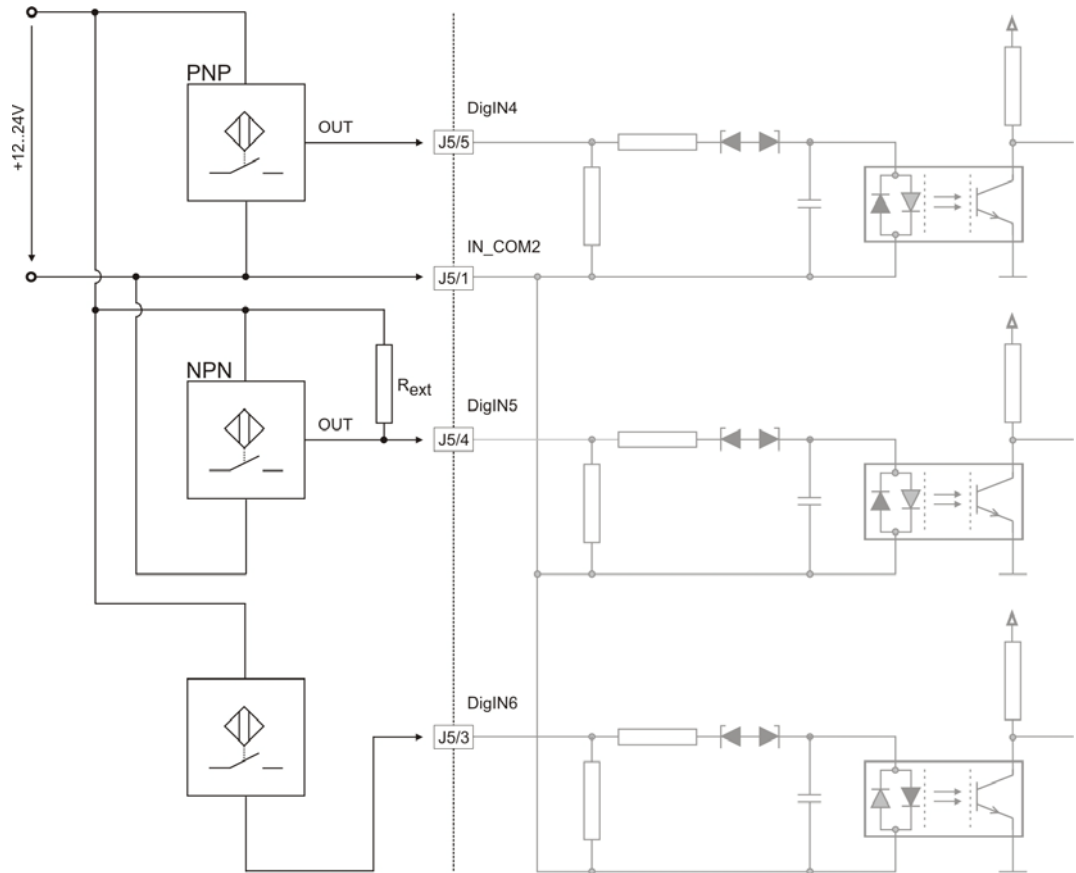


Figure 4-18 DigIN4...6 – Wiring Example for different Types of Proximity Switches



Best Practice

- Preferably, use 3-wire PNP proximity switches.
- Using 3-wire NPN proximity switches requires an additional pull-up resistor.
 $R_{ext} (12 V) = 560 \Omega (300 mW)$
 $R_{ext} (24 V) = 3 k\Omega (200 mW)$
- By principle, using 2-wire proximity switches is possible.

4.6.3 Supply Voltage for DigOUTs

For optically isolated digital outputs, an external supply voltage must be applied. Basically, any power supply may be used, provided it meets below stated minimal requirements.

+V Opto IN	Connector [J5] Pin [9]
DigOUT_Gnd	Connector [J5] Pin [14]
Supply voltage	+12...+24 VDC
Min. current	560 mA (depending on load)

4.6.4 Digital Outputs 1, 2 and 3

By default, the optically isolated digital outputs are defined as “General Purpose” and may be configured via software.

DigOUT1	Connector [J5] Pin [13]
DigOUT2	Connector [J5] Pin [12]
DigOUT3	Connector [J5] Pin [11]
+V Opto IN	Connector [J5] Pin [9]
Type of output	Optically isolated, open emitter
Output voltage	$U_{out} \geq (+V \text{ Opto IN} - 3 \text{ V})$
Max. load current	$I_{load} \leq 20 \text{ mA}$
Leakage current	$I_{leak} \leq 20 \mu\text{A}$
Switching delay	<500 μs @ 24 VDC

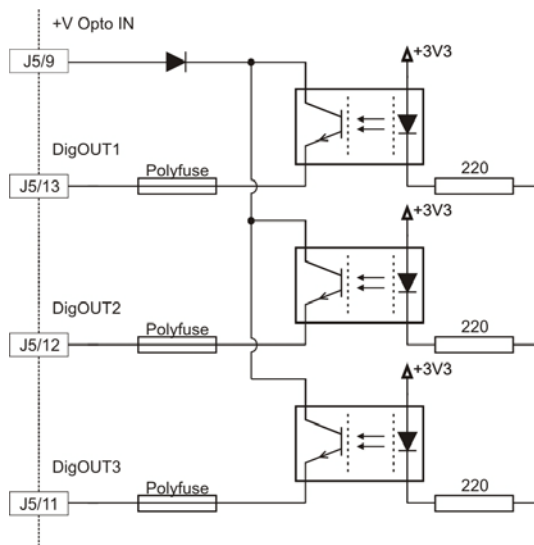


Figure 4-19 DigOUT1...3 Circuit

4.6.5 Digital Output 4

By default, the optically isolated digital output is defined as “Brake” (permanent DC voltage applied to serve as magnet brake) and may be configured via software.

DigOUT4	Connector [J5] Pin [10]
+V Opto IN	Connector [J5] Pin [9]
DigOUT_Gnd	Connector [J5] Pin [14]
Type of output	Optically isolated, open emitter
Output voltage	$U_{out} \geq (+V \text{ Opto IN} - 1 \text{ V})$
Max. load current	$I_{load} \leq 500 \text{ mA}$
Leakage current	$I_{leak} \leq 50 \mu\text{A}$
Switching delay	$< 300 \mu\text{s @ 24 VDC}$
Max. current load	2 H @ 24 VDC; 500 mA

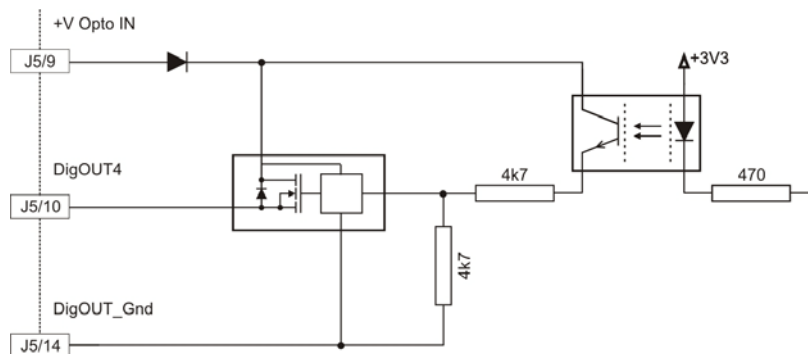


Figure 4-20 DigOUT4 Circuit

Wiring Example: “Permanent Magnet Brake”

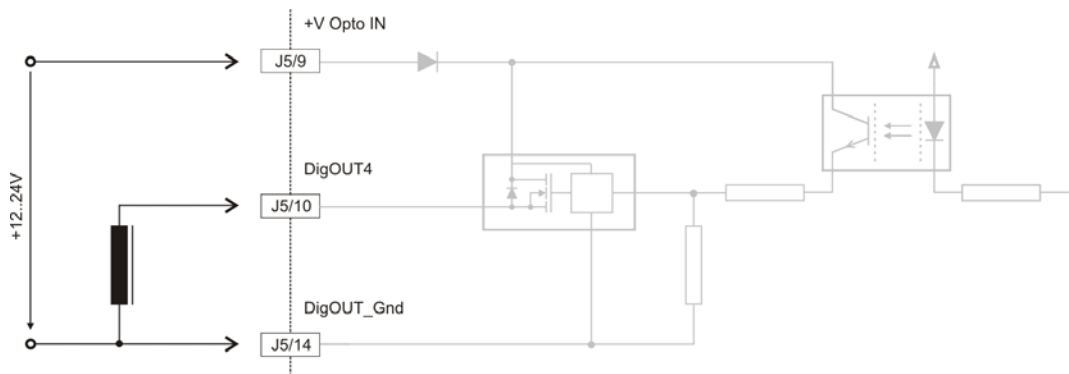


Figure 4-21 DigOUT4 – Wiring Example for Permanent Magnet Brake

4.6.6 Digital Input 11

By default, the optically isolated digital input is defined as “Power Stage Enable” and may be activated by internal DIP switch.

- DIP switch JP4, switch 2 “ON” (factory setting): “Power Stage Enable” deactivated
- DIP switch JP4, switch 2 “OFF”: “Power Stage Enable” activated

DigIN11 IN_COM3 (common signal)	Connector [J5] Pin [15] Connector [J5] Pin [16]
Type of input	Optically isolated, single-ended, bipolar
Input voltage	±24 VDC
Max. input voltage	±30 VDC
Logic 0	$ I_{in} < 1 \text{ mA} / U_{in} < 5 \text{ VDC}$
Logic 1	$ I_{in} > 3 \text{ mA} / U_{in} > 9 \text{ VDC}$
Input resistance	typically 1.8 kΩ @ 24 VDC
Input current at logic 1	typically 13.2 mA @ 24 VDC
Switching delay	<300 μs @ 24 VDC

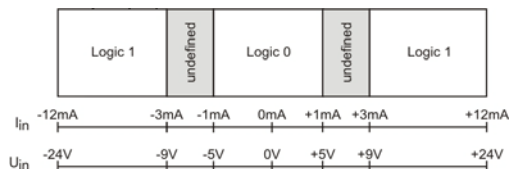


Figure 4-22 DigIN11 Logic Level

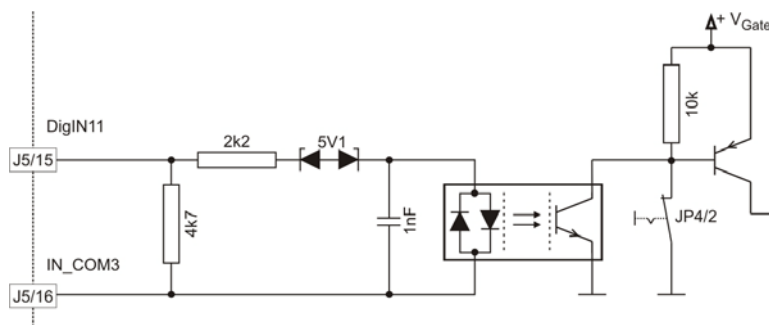


Figure 4-23 DigIN11 Circuit



Figure 4-24 DIP Switch JP4/2 – Factory Setting: “Power Stage Enable” deactivated

4.7 Signal 2 Connector (J5A)

Contains differential “High Speed Command” digital inputs.

Additionally available are differential analog inputs.

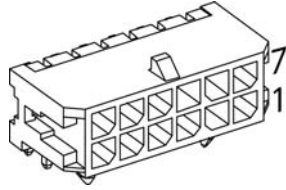


Figure 4-25 Signal 2 Connector (J5A)

Pin	Signal	Description
1	+5VOUT	Reference output voltage +5 V
2	A_Gnd	Analog signal ground
3	AnIN2-	Analog Input 2, negative signal
4	AnIN2+	Analog Input 2, positive signal
5	AnIN1-	Analog Input 1, negative signal
6	AnIN1+	Analog Input 1, positive signal
7	D_Gnd	Digital signal ground
8	D_Gnd	Digital signal ground
9	DigIN8/	Digital Input 8 “High Speed Command” complement
10	DigIN8	Digital Input 8 “High Speed Command”
11	DigIN7/	Digital Input 7 “High Speed Command” complement
12	DigIN7	Digital Input 7 “High Speed Command”

Accessories	Cable	EPOS Signal Cable 2 (300586)
Notes	Suitable connector Suitable crimp terminals Suitable hand crimper	Molex Micro-Fit 3.0 12 poles (430-25-1200) Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx) Molex hand crimper (63819-0000)

4.7.1 Reference Output Voltage

Can be used as supply voltage for external loads connected to EPOS2 70/10 analog inputs.

+5VOUT	Connector [J5A] Pin [1]
Output voltage	+5 VDC
Output resistance	1.0 kΩ

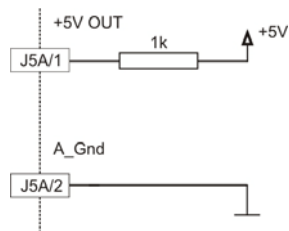


Figure 4-26 Reference Output Voltage Circuit

4.7.2 Analog Inputs 1 and 2

By default, the analog inputs are defined as "General Purpose" and may be configured via software.

AnIN1+	Connector [J5A] Pin [5]
AnIN1-	Connector [J5A] Pin [6]
AnIN2+	Connector [J5A] Pin [3]
AnIN2-	Connector [J5A] Pin [4]
Input voltage	0...5 VDC (differential)
Max. input voltage	±30 VDC
Common mode voltage	-5 ...+10 VDC (referenced to A_Gnd)
Input resistance	30.2 kΩ (differential) 24.2 kΩ (referenced to A_Gnd)
A/D converter	12-bit
Resolution	1.22 mV
Bandwidth	5 kHz

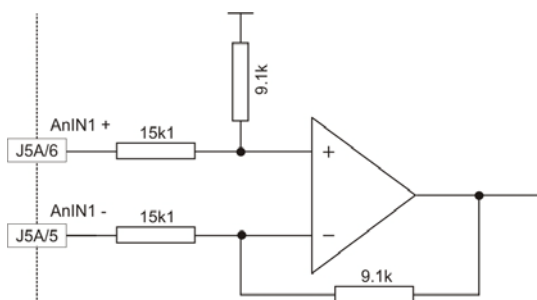


Figure 4-27 AnIN1 Circuit (analogously valid also for AnIN2)

4.7.3 Digital Inputs 7 and 8 “High Speed Command”

The “High Speed Command” differential inputs are set by default and may be configured via software.

Differential	
DigIN7 “High Speed Command”	Connector [J5A] Pins [9] / [10]
DigIN8 “High Speed Command”	Connector [J5A] Pins [11] / [12]
Min. differential input voltage	±200 mV
Line receiver (internal)	EIA RS422 Standard
Max. input frequency	5 MHz

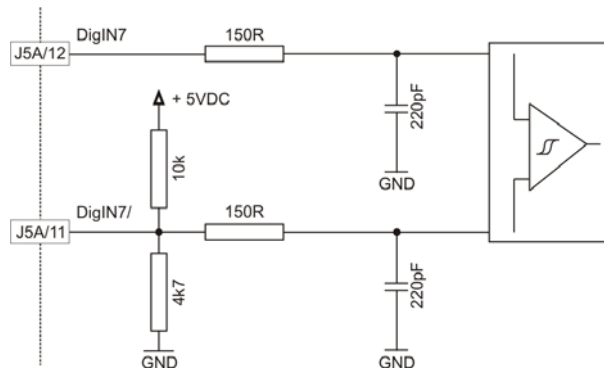


Figure 4-28 DigIN7 “Differential” Circuit (analogously valid also for DigIN8)

Sin/Cos	
Input voltage	±1.8 V (differential)
Max. input voltage	±12 VDC
Common mode voltage	-1...+4 VDC (referenced to D_Gnd)
Input resistance	>10 kΩ (differential)
A/D converter	12-bit
Resolution	0.88 mV
Bandwidth	5 kHz

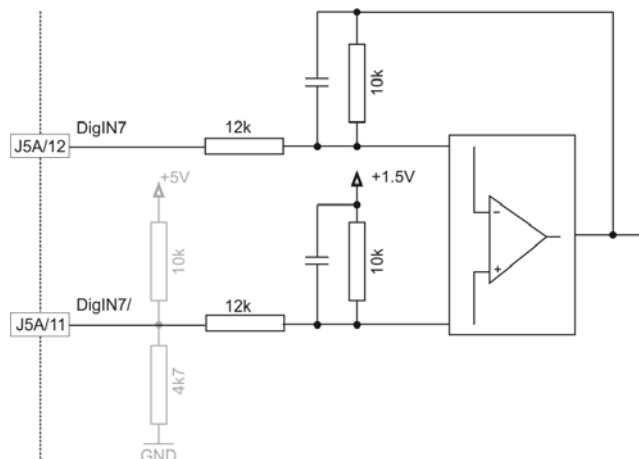


Figure 4-29 DigIN7 “Sin/Cos” Circuit (analogously valid also for DigIN8)

Single-ended	
Input voltage	0...5 VDC
Max. input voltage	±12 VDC
Logic 0	<1.0 V
Logic 1	>2.4 V
Input high current	I_{IH} = typically +350 μ A @ 5 V
Input low current	I_{IL} = typically -130 μ A @ 0 V
Max. input frequency	2.5 MHz

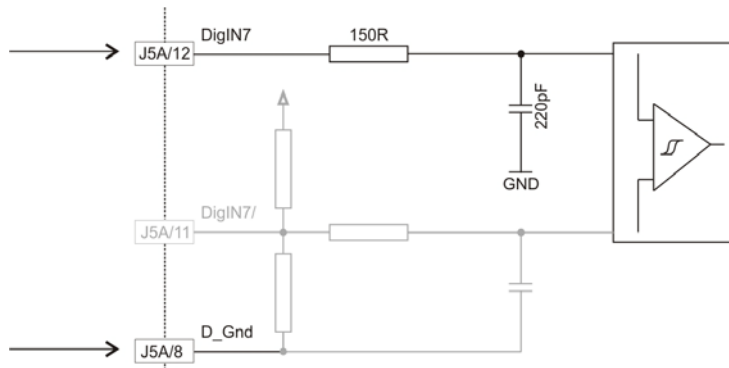


Figure 4-30 DigIN7 “Single-ended” Circuit (analogously valid also for DigIN8)

4.8 Signal 3 Connector (J5B)

Contains differential “High Speed Command” digital I/Os.

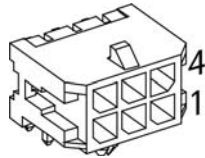


Figure 4-31 Signal 3 Connector (J5B)

Pin	Signal	Description
1	DigIN9/	Digital Input 9 “High Speed Command” complement
2	DigIN9	Digital Input 9 “High Speed Command”
3	DigOUT5/	Digital Output 5 “High Speed Output” complement
4	+V _{AUX}	Auxiliary output voltage +5DC / 150 mA
5	D_Gnd	Digital signal ground
6	DigOUT5	Digital Output 5 “High Speed Output”

Accessories	Cable	EPOS2 Signal Cable 4 (378173)
Notes	Suitable connector Suitable crimp terminals Suitable hand crimper	Molex Micro-Fit 3.0 6 poles (430-25-0600) Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx) Molex hand crimper (69819-0000)

4.8.1 Digital Input 9 “High Speed Command”

By default, the differential input is set as “High Speed Command” and may be configured via software.

Differential	
DigIN9 “High Speed Command”	Connector [J5B] Pins [1] / [2]
Min. differential input voltage	±200 mV
Line receiver (internal)	EIA RS422 Standard
Max. input frequency	5 MHz

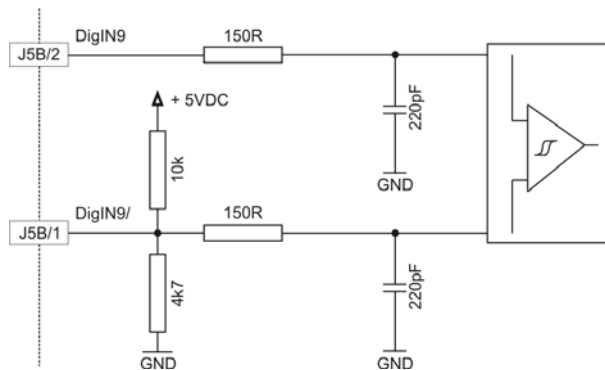


Figure 4-32 DigIN9 “Differential” Circuit

Single-ended	
DigIN9 “High Speed Command”	Connector [J5B] Pins [1] / [2]
Input voltage	0...5 VDC
Max. input voltage	±12 VDC
Logic 0	<1.0 V
Logic 1	>2.4 V
Input high current	I_{IH} = typically +60 μ A @ 5 V
Input low current	I_{IL} = typically 0 A @ 0 V
Max. input frequency	2.5 MHz

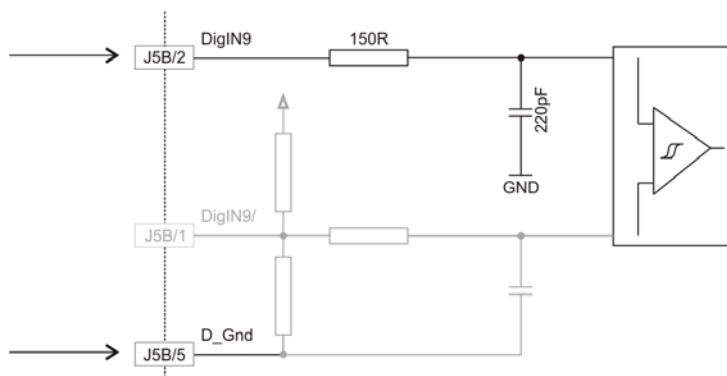


Figure 4-33 DigIN9 “Single-ended” Circuit

4.8.2 Auxiliary Output Voltage

Can be used as supply voltage for external loads connected to EPOS2 70/10 digital inputs.

+V _{AUX}	Connector [J5B] Pin [4]
Output voltage	+5 VDC (referenced to D_Gnd)
Output current	max. 150 mA

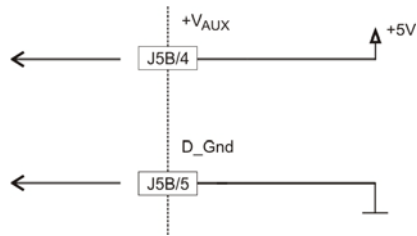


Figure 4-34 Auxiliary Output Voltage Circuit

4.8.3 Digital Output 5 “High Speed Output”

By default, the differential output is set as “High Speed Output” and may be configured via software.

Differential	
DigOUT5 “High Speed Output”	Connector [J5B] Pins [3] / [6]
Differential output voltage	min 1.5 V @ $R_L = 54 \Omega$
Output current	max. 60 mA
Line transceiver (internal)	EIA RS422 Standard
Max. output frequency	5 MHz

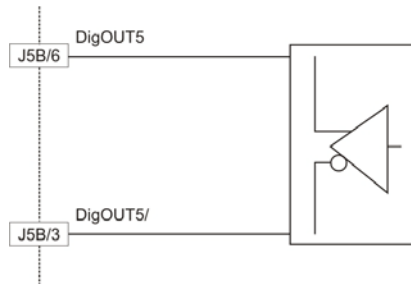


Figure 4-35 DigOUT5 “Differential” Circuit

Single-ended	
DigOUT5 “High Speed Output”	Connector [J5B] Pins [3] / [6]
Output voltage	+5 VDC @ 0 mA
Max. load current	±60 mA
Logic 0	<2.0 V @ 60 mA (sink)
Logic 1	>2.5 V @ 60 mA (source)

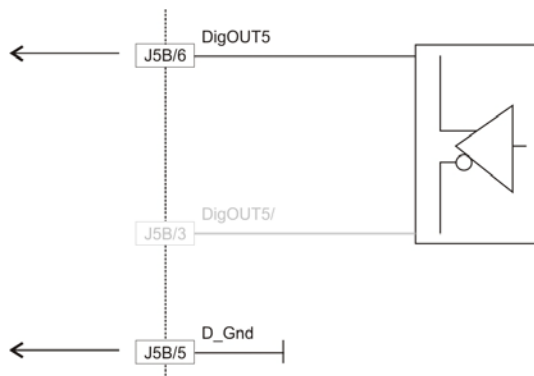


Figure 4-36 DigOUT5 “Single-ended” Circuit

4.9 RS232 Connector (J6)

Max. input voltage	±24 V
Output voltage	typically ±9 V @ 3 kΩ to Ground
Max. bit rate	115 200 bit/s
Internal RS232 driver/receiver	EIA RS232 Standard

Connection of Positioning Controller to PC

EPOS2 70/10	PC Interface (RS232), DIN41652
Connector [J6] Pins [4] + [5] "GND"	Pin 5 "GND"
Connector [J6] Pin [1] "EPOS RxD"	Pin 3 "PC TxD"
Connector [J6] Pin [2] "EPOS TxD"	Pin 2 "PC RxD"



Note

- Consider your PC's serial port maximal baud rate.
- The standard baud rate setting (factory setting) is 115'200 bauds.

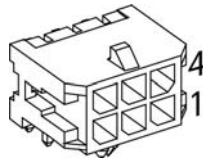


Figure 4-37 RS232 Connector (J6)

Pin	Signal	Description
1	EPOS RxD	EPOS RS232 receive
2	EPOS TxD	EPOS RS232 transmit
3	not connected	–
4	GND	RS232_Ground
5	GND	RS232_Ground
6	Shield	Cable shield

Accessories	Cable	EPOS RS232-COM Cable (275900)
Notes	Suitable connector Suitable crimp terminals Suitable hand crimper	Molex Micro-Fit 3.0 6 poles (430-25-0600) Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx) Molex hand crimper (63819-0000)

4.10 CAN Connector (J7, J8)

Standard type	CAN high-speed, ISO 11898 compatible
Max. bit rate	1 Mbit/s
Max. number of CAN nodes	127
Protocol	CANopen DS-301 V4.02
Identifier setting	DIP switch or software

Connection of Positioning Controller to CAN Bus Line CiA DS-102

EPOS2 70/10	CAN 9 pin D-Sub (DIN41652)
Connector [J7] or [J8] Pin [1] "CAN high"	Pin 7 "CAN_H" high bus line
Connector [J7] or [J8] Pin [2] "CAN low"	Pin 2 "CAN_L" low bus line"
Connector [J7] or [J8] Pin [3] "CAN GND"	Pin 3 "CAN_GND" Ground
Connector [J7] or [J8] Pin [4] "CAN shield"	Pin 5 "CAN_Shield" cable shield



Note

- Consider CAN Master's maximal baud rate.
- The standard baud rate setting (factory setting) is "Auto Bit Rate".
- Use termination resistor at both ends of the CAN bus (→chapter "4.12.2 CAN Bus Termination" on page 4-41).
- For detailed CAN information →separate document «EPOS2 Communication Guide».

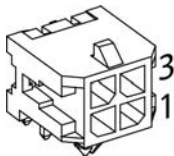


Figure 4-38 CAN Connector (J7/J8)

Pin	Signal	Description
1	CAN high	CAN high bus line
2	CAN low	CAN low bus line
3	CAN GND	CAN Ground
4	CAN shield	Cable shield

Accessories	Cables	EPOS CAN-COM Cable (275908) EPOS CAN-CAN Cable (275926) EPOS CAN Termination Plug (275937)
Notes	Suitable connector Suitable crimp terminals Suitable hand crimper	Molex Micro-Fit 3.0 4 poles (430-25-0400) Molex Micro-Fit 3.0 female crimp terminals (43030-xxxx) Molex hand crimper (63819-0000)

4.11 USB Connector (J9)

USB Standard	2.0 (Full Speed)
Max. bit rate	12 Mbit/s
Max. bus supply voltage	+5.25 VDC
Typical input current	15 mA
Max. DC data input voltage	-0.5...+3.8 VDC

Connection of Positioning Controller to PC

EPOS2 70/10	PC Interface (USB 2.0)
Connector [J9] Pin [1] "V _{BUS} "	Pin 1 "V _{BUS} "
Connector [J9] Pin [2] "USB D-"	Pin 2 "USB D-"
Connector [J9] Pin [3] "USB D+"	Pin 3 "USB D+"
Connector [J9] Pin [5] "GND"	Pin 4 "GND"
Connector [J9] Housing "Shield"	Housing "Shield"



Figure 4-39 USB Connector (J9)

Pin	Signal	Description
1	V _{BUS}	USB bus supply input voltage +5 VDC
2	USB D-	USB Data-
3	USB D+	USB Data+
4	not connected	–
5	GND	USB Ground
	Shield	Cable Shield

Accessories	Cable	EPOS2 USB Type A-mini B Cable (370513)
Notes	Suitable connector	Standard USB cable with type mini B plug (5 poles)

4.12 CAN Configuration (JP1)

4.12.1 CAN ID (Node Address)

The CAN ID is set with DIP switches 1...7. Addresses (1...127) may be coded using binary code.



Note

- By setting the DIP switch (1...7) address 0 (“OFF”), the CAN ID may be configured by software (changing object “Node ID”, range 1...127).
- The CAN ID results in the summed values of DIP switch addresses 1 (“ON”).
- DIP switch 8 does not have any impact on the CAN ID.

Switch	Binary Code	Valence
1	2^0	1
2	2^1	2
3	2^2	4
4	2^3	8
5	2^4	16
6	2^5	32
7	2^6	64

Table 4-14 CAN ID – Binary Code Values

Examples:

Use following table as a (non-concluding) guide:




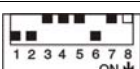
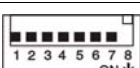
CAN ID	DIP Setting	CAN ID/Switch								Calculation
		1	2	3	4	5	6	7	Valence	
1		1	0	0	0	0	0	0	0	1
2		0	1	0	0	0	0	0	0	2
32		0	0	0	0	0	1	0	0	32
35		1	1	0	0	0	1	0	0	1 + 2 + 32
127		1	1	1	1	1	1	1	1	1 + 2 + 4 + 8 + 16 + 32 + 64

Table 4-15 CAN ID – DIP Switch Settings (Example)

4.12.2 CAN Bus Termination

The CAN bus must be terminated at both ends by a termination resistor of 120 Ω, typically. Depending on utilization of the controller, individual CAN bus termination settings must be performed.

Using DIP switch 8, the controller-internal bus termination resistor can be activated/deactivated. By default, bus termination is “OFF”, nevertheless, the bus is **not** terminated.

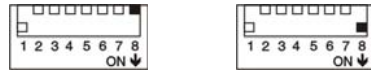


Figure 4-40 DIP Switch (JP1 [8]) – CAN Bus Termination (left “OFF” / right “ON”)

Example 1: Multiple Axis System with EPOS2 70/10 within CANopen Bus

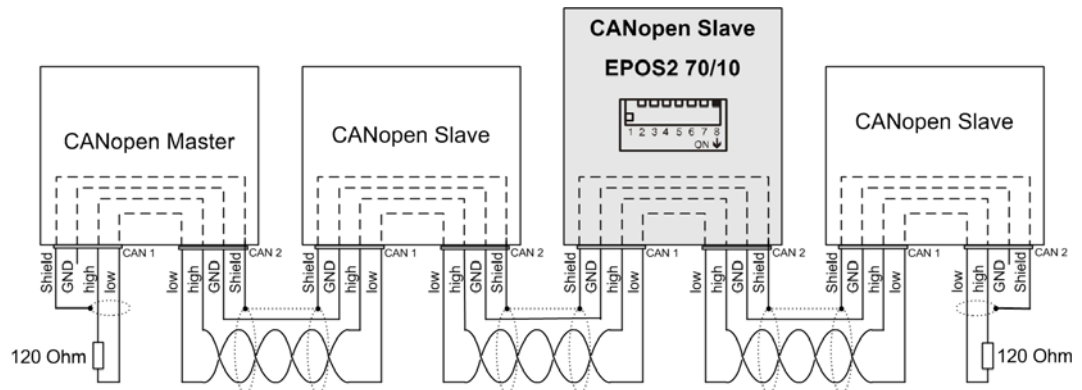


Figure 4-41 EPOS2 70/10 without CAN Bus Termination

Example 2: Multiple Axis System with EPOS2 70/10 both Ends of CANopen Bus

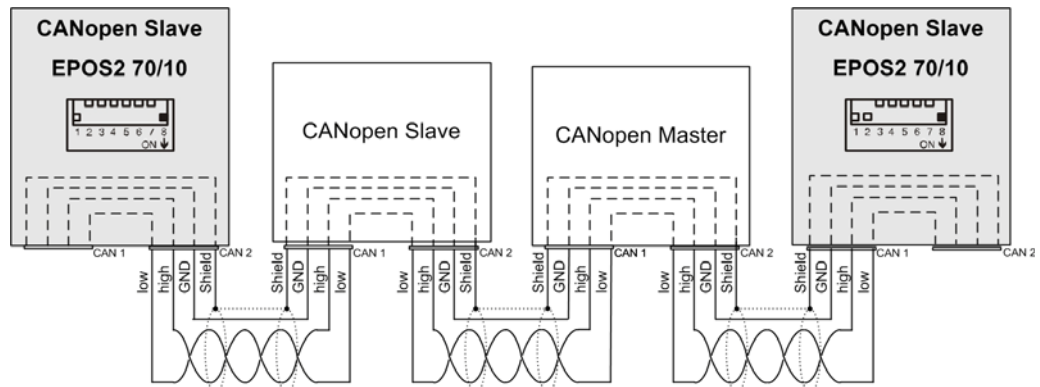


Figure 4-42 EPOS2 70/10 with CAN Bus Termination

4.13 Status LEDs

The LEDs display the current status of the EPOS2 70/10 as well as possible errors:

- Green LED shows the operating status
- Red LED indicates errors



For detailed information → separate document «EPOS2 Firmware Specification».

LED		Status / Error
Red	Green	
OFF	Slow	Power stage is disabled. Device is in status... • “Switch ON Disabled” • “Ready to Switch ON” • “Switched ON”
OFF	ON	Power stage is enabled. Device is in status... • “Operation Enable” • “Quick Stop Active”
ON	OFF	FAULT state. Device is in status... • “Fault”
ON	ON	Power stage is enabled. Device is in temporary status... • “Fault Reaction Active”
ON	Flash	No valid firmware or firmware download in progress.
Flash = Flashing (≈0.9 s OFF/≈0.1 s ON) Slow = Slow blinking (≈1 Hz)		

Table 4-16 LEDs – Interpretation of Condition

LIST OF FIGURES

Figure 2-1 Documentation Structure 9

Figure 3-2 Dimensional Drawing [mm]. 14

Figure 4-3 Interfaces – Designations and Location 15

Figure 4-4 Wiring Diagram 15

Figure 4-5 Power Connector (J1). 16

Figure 4-6 Power Connector (J1A) 17

Figure 4-7 Motor Connector (J2) 18

Figure 4-8 Hall Sensor Input Circuit. 19

Figure 4-9 Hall Sensor Connector (J3) 19

Figure 4-10 Encoder Input Circuit for Channel A (analogously valid also for Channel B) 20

Figure 4-11 Encoder Input Circuit for Index Channel. 20

Figure 4-12 Encoder Connector (J4) 21

Figure 4-13 Signal 1 Connector (J5) 22

Figure 4-14 DigIN1...3 Logic Level 23

Figure 4-15 DigIN1...3 Circuit 23

Figure 4-16 DigIN4...6 Logic Level 24

Figure 4-17 DigIN4...6 Circuit 24

Figure 4-18 DigIN4...6 – Wiring Example for different Types of Proximity Switches. 25

Figure 4-19 DigOUT1...3 Circuit 26

Figure 4-20 DigOUT4 Circuit 27

Figure 4-21 DigOUT4 – Wiring Example for Permanent Magnet Brake 27

Figure 4-22 DigIN11 Logic Level 28

Figure 4-23 DigIN11 Circuit 28

Figure 4-24 DIP Switch JP4/2 – Factory Setting: “Power Stage Enable” deactivated. 28

Figure 4-25 Signal 2 Connector (J5A) 29

Figure 4-26 Reference Output Voltage Circuit. 29

Figure 4-27 AnIN1 Circuit (analogously valid also for AnIN2) 30

Figure 4-28 DigIN7 “Differential” Circuit (analogously valid also for DigIN8) 31

Figure 4-29 DigIN7 “Sin/Cos” Circuit (analogously valid also for DigIN8) 31

Figure 4-30 DigIN7 “Single-ended” Circuit (analogously valid also for DigIN8) 32

Figure 4-31 Signal 3 Connector (J5B) 33

Figure 4-32 DigIN9 “Differential” Circuit 34

Figure 4-33 DigIN9 “Single-ended” Circuit 34

Figure 4-34 Auxiliary Output Voltage Circuit 35

Figure 4-35 DigOUT5 “Differential” Circuit 36

Figure 4-36 DigOUT5 “Single-ended” Circuit 36

Figure 4-37 RS232 Connector (J6) 37

Figure 4-38 CAN Connector (J7/J8) 38

Figure 4-39 USB Connector (J9) 39

Figure 4-40 DIP Switch (JP1 [8]) – CAN Bus Termination (left “OFF” / right “ON”) 41

Figure 4-41 EPOS2 70/10 without CAN Bus Termination 41

Figure 4-42 EPOS2 70/10 with CAN Bus Termination. 41

LIST OF TABLES

Table 1-1 Notations used in this Document 5
Table 1-2 Brand Names and Trademark Owners. 7
Table 3-3 Electrical Data – Rating 11
Table 3-4 Electrical Data – Inputs 11
Table 3-5 Electrical Data – Outputs 12
Table 3-6 Electrical Data – Voltage Outputs 12
Table 3-7 Electrical Data – Motor Connections 12
Table 3-8 Electrical Data – Interfaces 12
Table 3-9 Electrical Data – LEDs 12
Table 3-10 Electrical Data – Connections 13
Table 3-11 Mechanical Data. 14
Table 3-12 Environmental Conditions 14
Table 3-13 Order Details 14
Table 4-14 CAN ID – Binary Code Values 40
Table 4-15 CAN ID – DIP Switch Settings (Example) 40
Table 4-16 LEDs – Interpretation of Condition 42

INDEX

A

additionally applicable regulations **10**
alerts **5**
analog inputs **30**

B

backup power **17**
bus termination **41**

C

cable
 275829 **16, 17**
 275851 **18**
 275878 **19**
 275900 **37**
 275908 **38**
 275926 **38**
 275932 **22**
 275934 **21**
 275937 **38**
 300586 **29**
 378173 **33**
calculation of required supply voltage **16**
CAN
 bus termination **41**
 interface **38**
CAN ID settings **40**

connector

- J1 **16**
- J1A **17**
- J2 **18**
- J3 **19**
- J4 **20**
- J5 **22**
- J5A **29**
- J5B **33**
- J6 **37**
- J7 **38**
- J8 **38**
- J9 **39**

country-specific regulations **10**

D

digital inputs **23, 24**
digital outputs **26, 27**
DIP switch
 JP1 **40**
 JP1, bus termination **41**

E

electrical data **11**
encoders, suitable types **21**
environmental conditions, permitted **14**
error display **42**
ESD **10**
example
 setting CAN IDs **40**
 terminating CANopen bus **41**
 wiring permanent magnet brake **27**
 wiring proximity switches **25**

H

how to
 calculate required supply voltage **16**
 configure CAN ID **40**
 interpret icons (and signs) used in the document **5**

I

informatory signs **6**
intended purpose **9**
interface
 CAN **38**
 RS232 **37**
 USB **39**
interfaces, location and designation **15**

L

LEDs **42**

M

mandatory action signs **6**
mechanical data **14**

N

Node Address, configuration **40**

O

operating status, display **42**

P

performance data **11**
power backup **17**
precautions **10**
prohibitive signs **6**
purpose
 of the device **9**
 of this document **5**

R

regulations, additionally applicable **10**

RS232

interface **37**

S

safety alerts **5**

safety first! **10**

signs

informative **6**

mandatory **6**

prohibitive **6**

signs used **5**

status display **42**

status LEDs **42**

supply voltage, required **16**

symbols used **5**

T

technical data **11**

U

USB

interface **39**

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